

# Keys for designing the most efficient and robust in-situ TP ATP.

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WOLFTP Project (FUI 16), Macothec (FUI 14)  
(Winding and Optimization Laser Thermoplastic Placement)

CIFRE PhD with Ariane Group



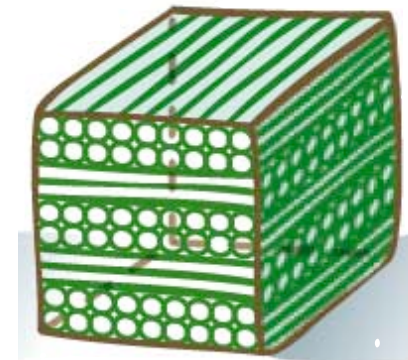
Modelisation & Simulation of the process  
(Thermo-Mechanical - Micro Mechanical)

# Applications

Need to manufacture complex form parts

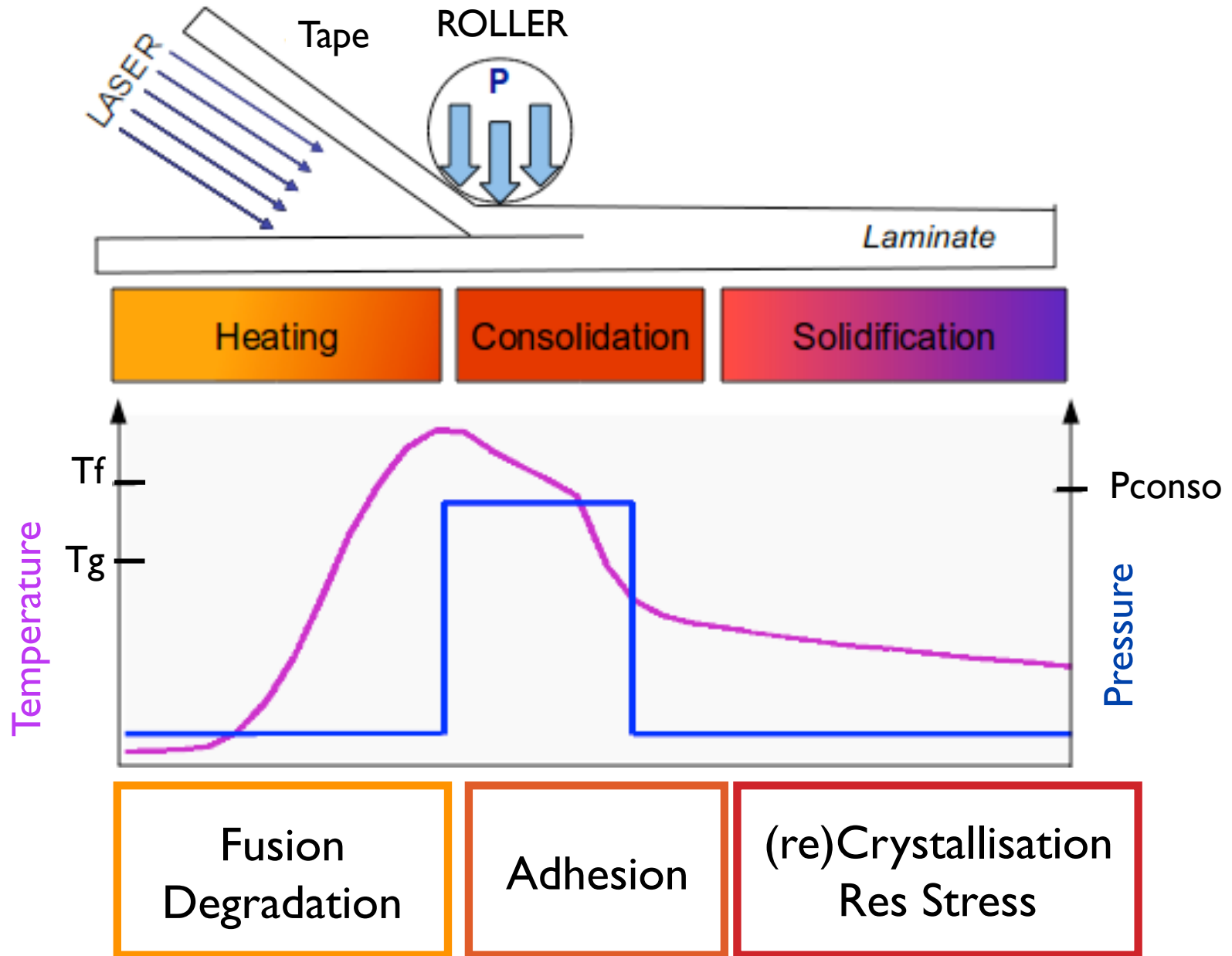
Laminated composite parts

Complex geometry

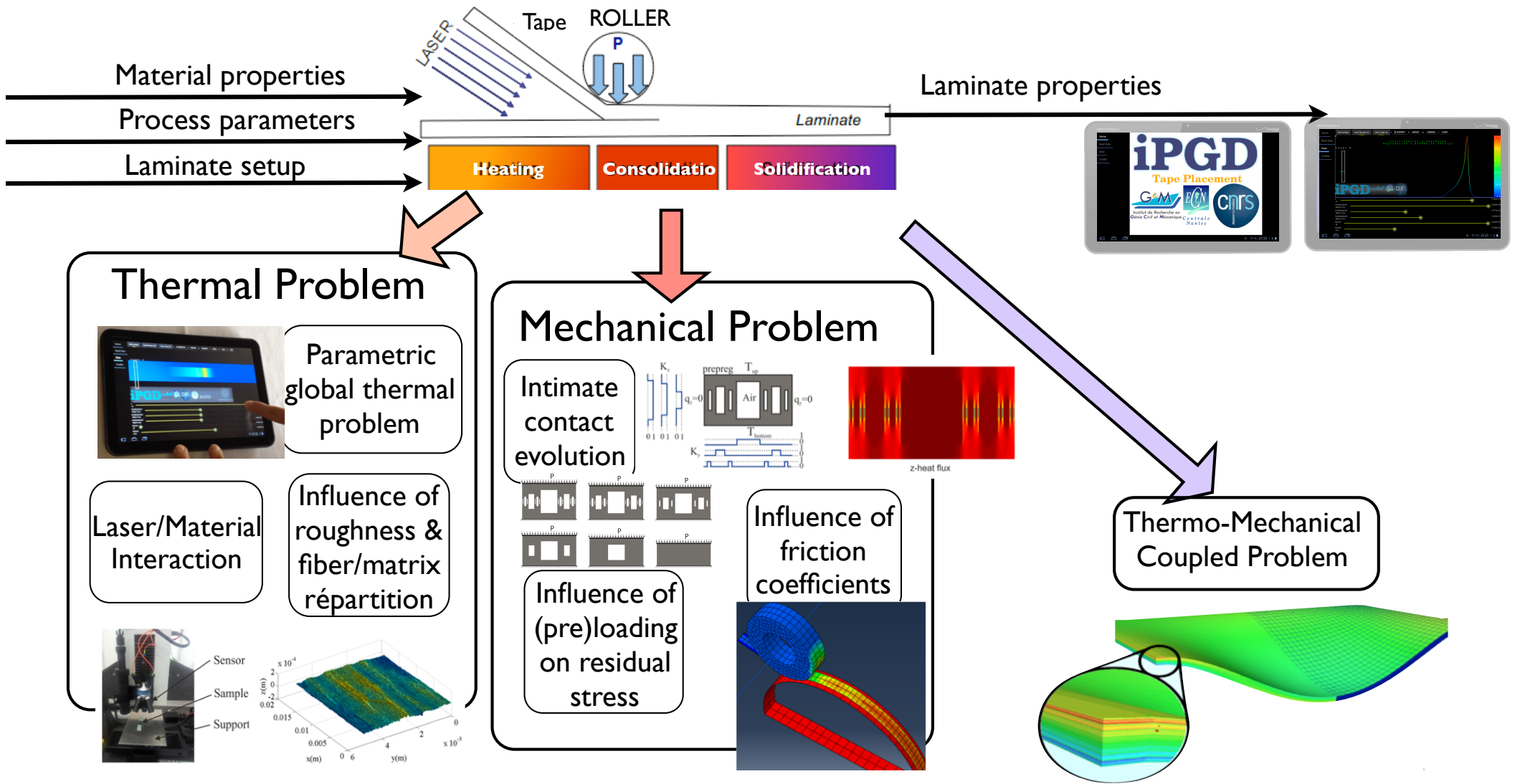


Identify the key parameters for efficient manufacturing

# Comprehension ATP Process : Forming steps



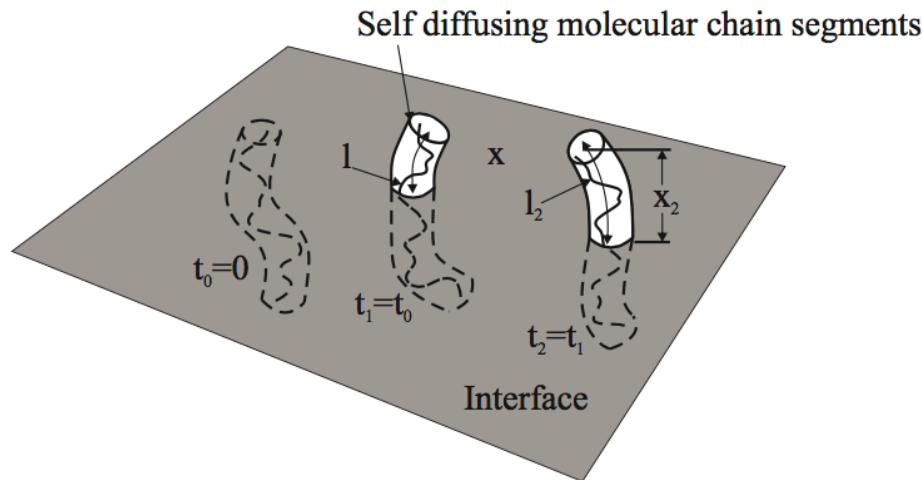
# Automated Tape Placement - Overview



Also: Ray-Tracing 3D, Roller Compaction, Process variability,...

# Framework Focus

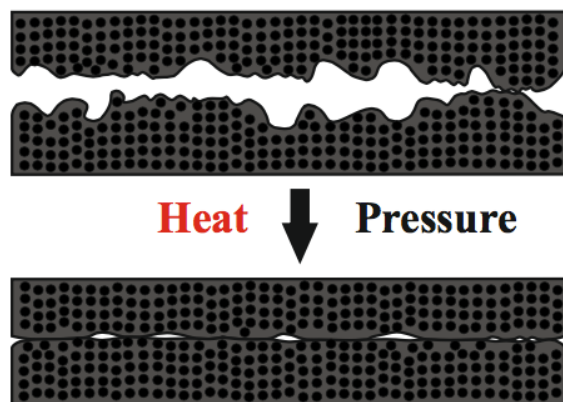
## Healing



- Molecules diffuse across the interface
- Reptation theory depends on temperature

$$D_h = K(T) \cdot (t)^{1/4}$$

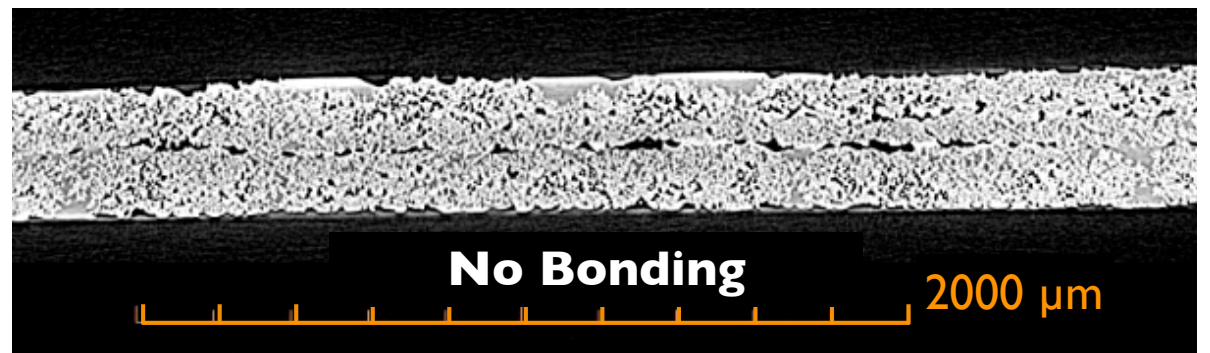
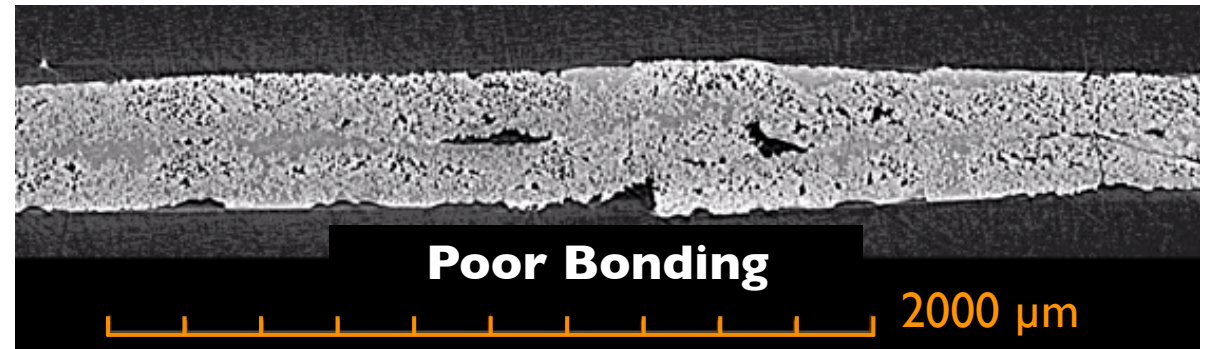
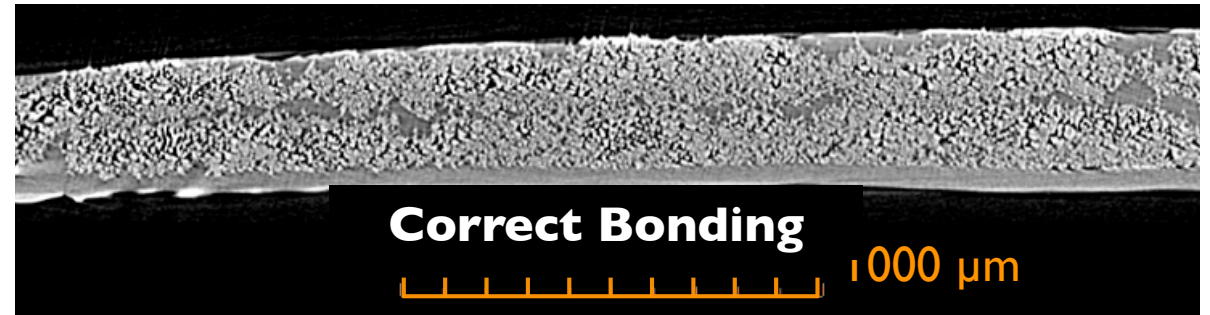
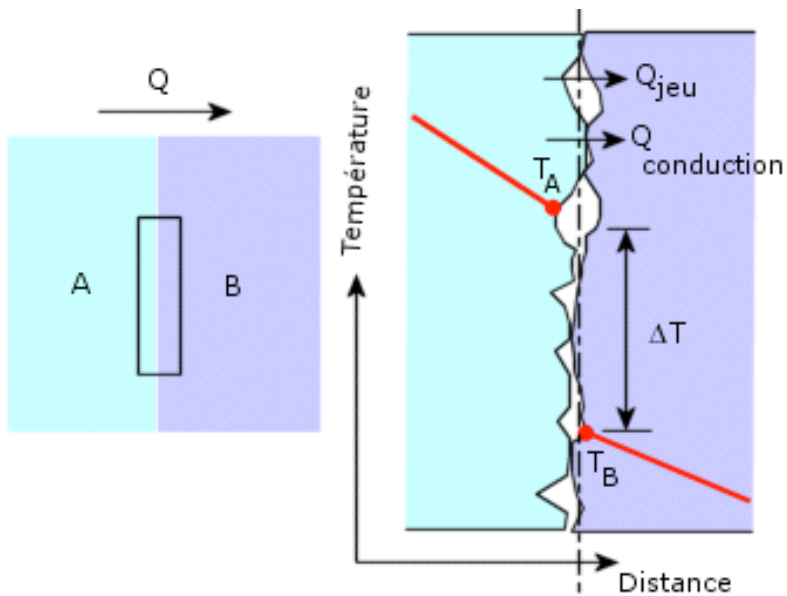
## Intimate Contact



- Evolution of area in contact
- Viscosity depends on temperature

# Main point to follow

## Thermal contact resistance



# Wavelet Representation

The interface can be represented in a set of basis that expresses the different levels (different scales) of the surface. **Multilevel representation**

$$V_m = V_0 \oplus W_1 \dots W_{m-3} \oplus W_{m-2} \oplus W_{m-1} \oplus W_m$$

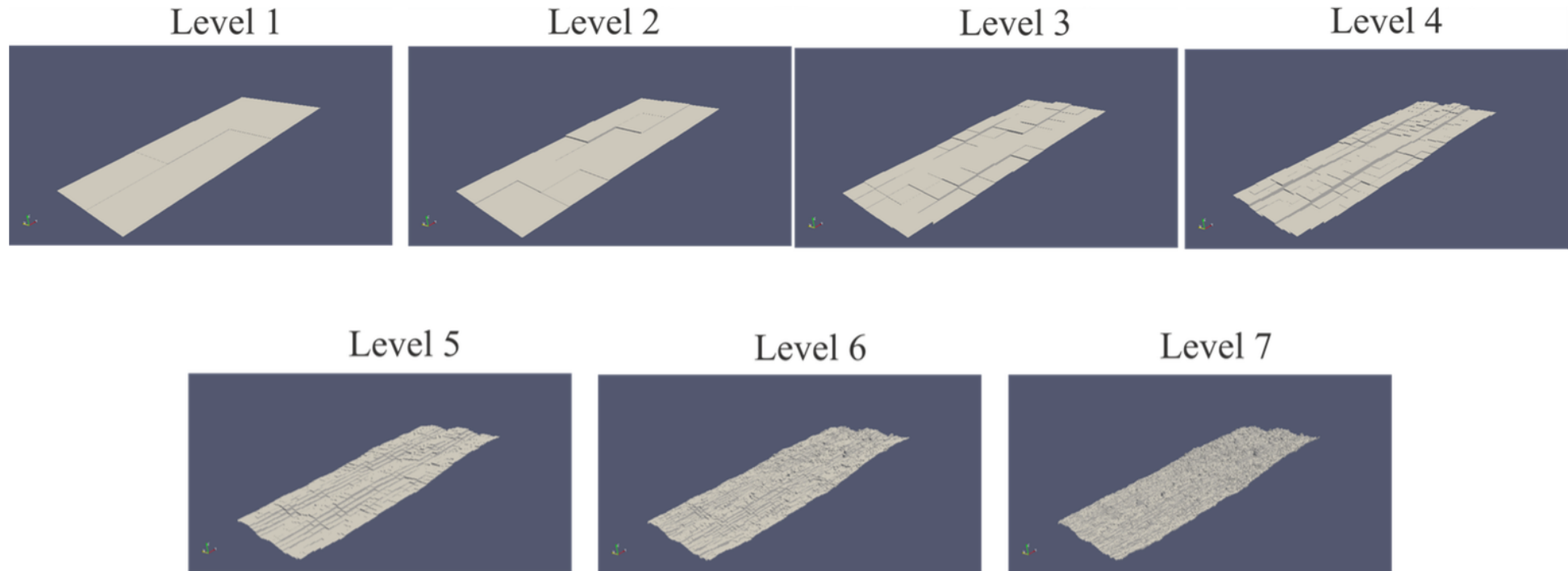
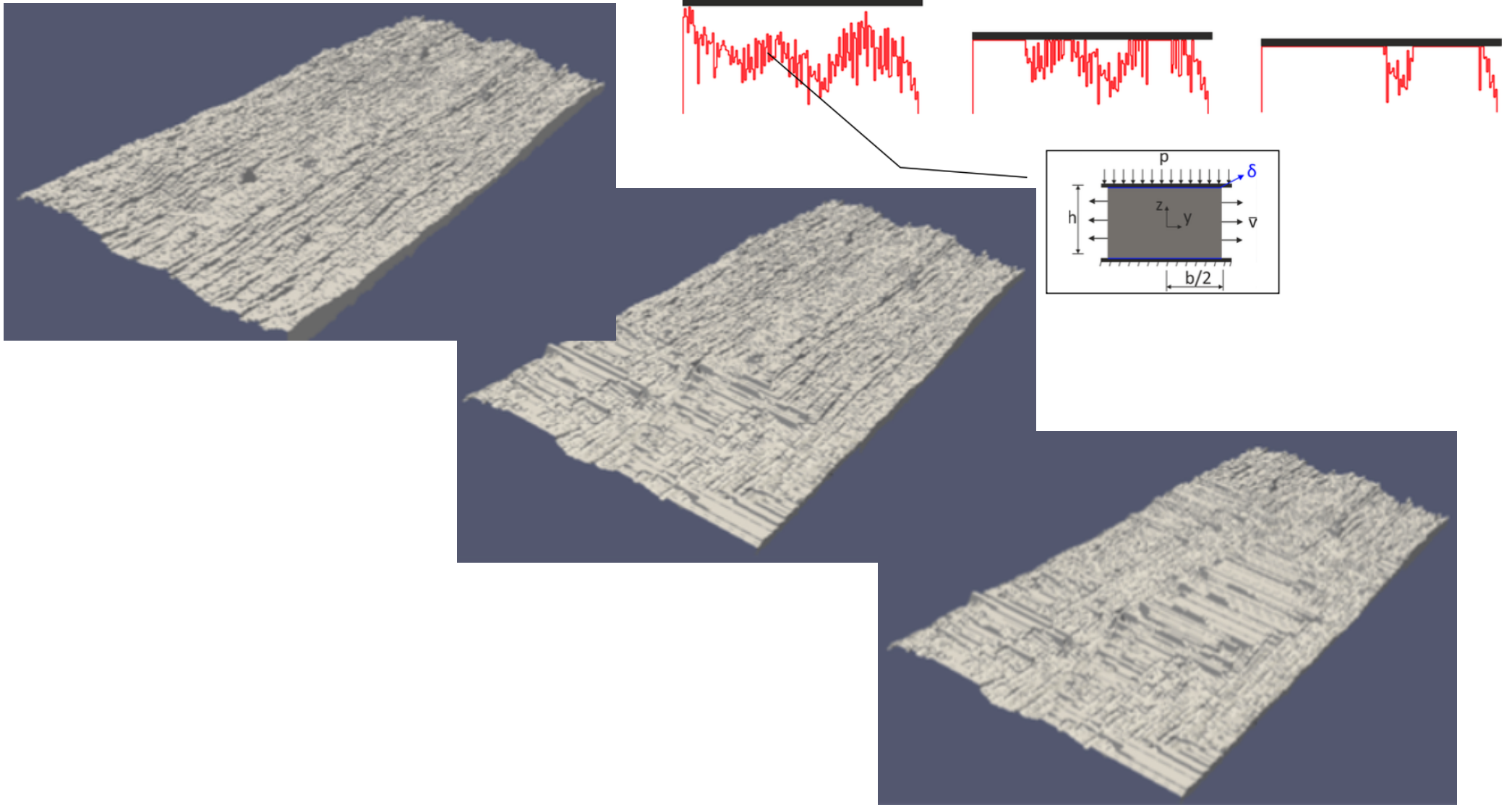


Figure 11: Interface expressed by wavelet basis at different levels



# Compression of the interface



We considered a squeeze flow for each asperity assuming lubrication hypothesis.

# Compression of the interface

The temperature field is solved by applying PGD with different material conductivities, avoiding the distortion of the mesh.

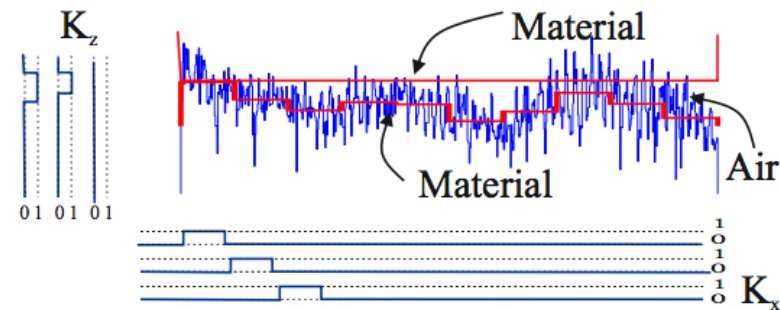
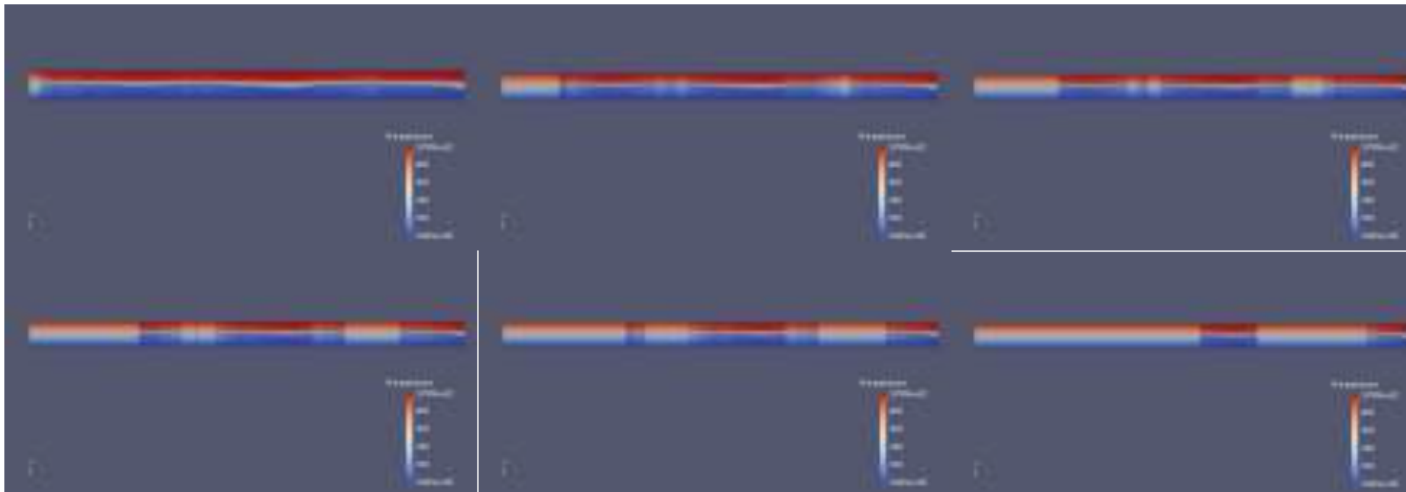


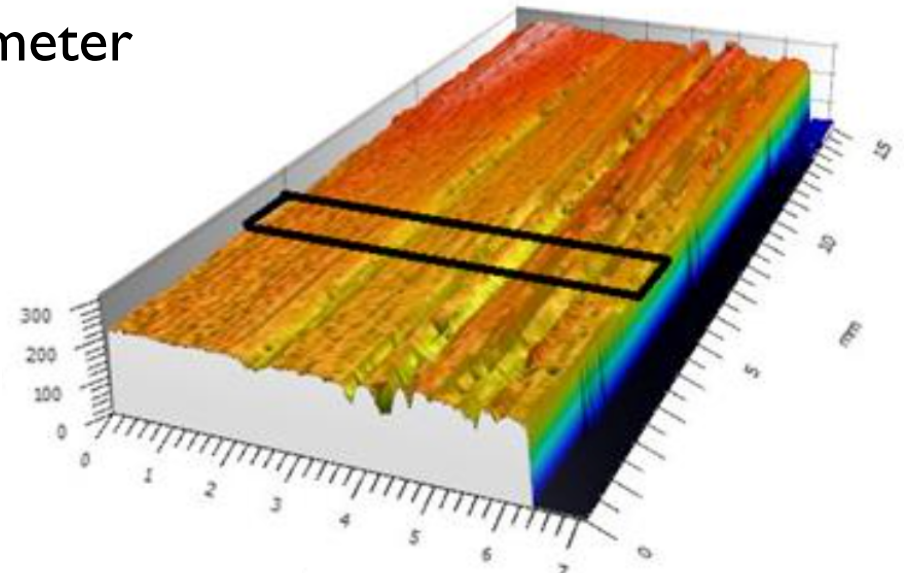
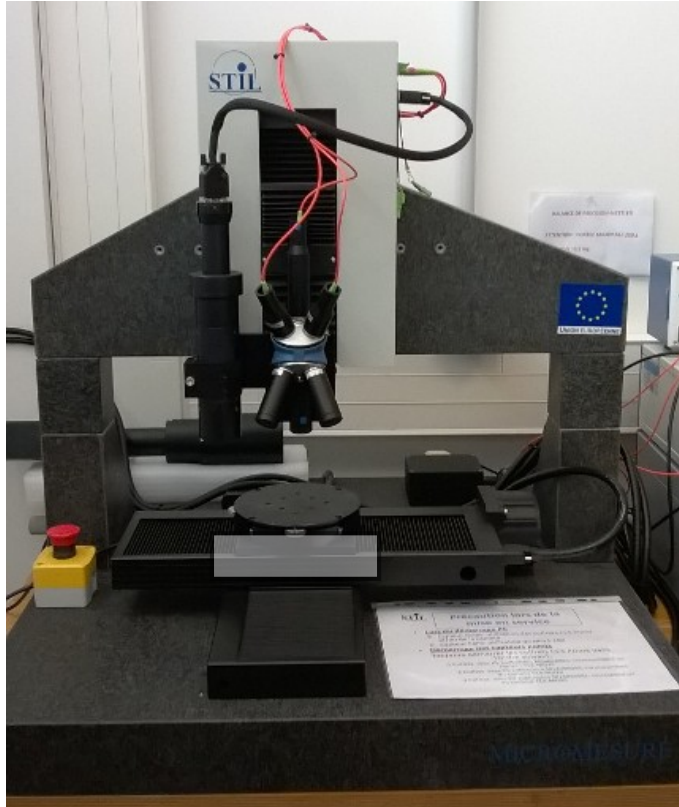
Figure 5: PGD material conductivities for representing the real geometry

Evolution of the temperature. 30 times amplification in Z



# Characterization of the interface

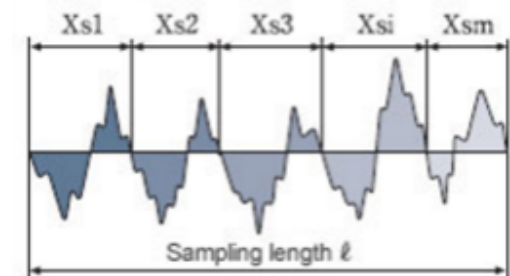
The surface is scanned by an optical profilometer



$$R_a = \frac{1}{N} \sum_{j=1}^N |r_j|$$

$$R_t = \left| \min_{1 \leq j \leq N} r_j \right| + \left| \max_{1 \leq j \leq N} r_j \right|$$

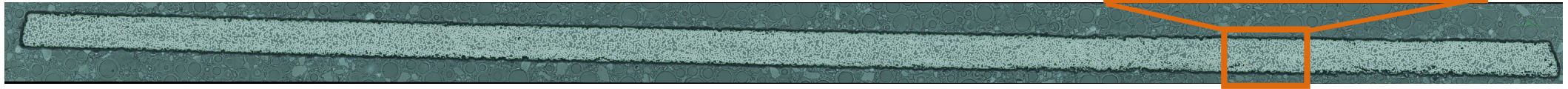
$$R_{Sm} = \frac{1}{m} \sum_{i=1}^m X_{si}$$



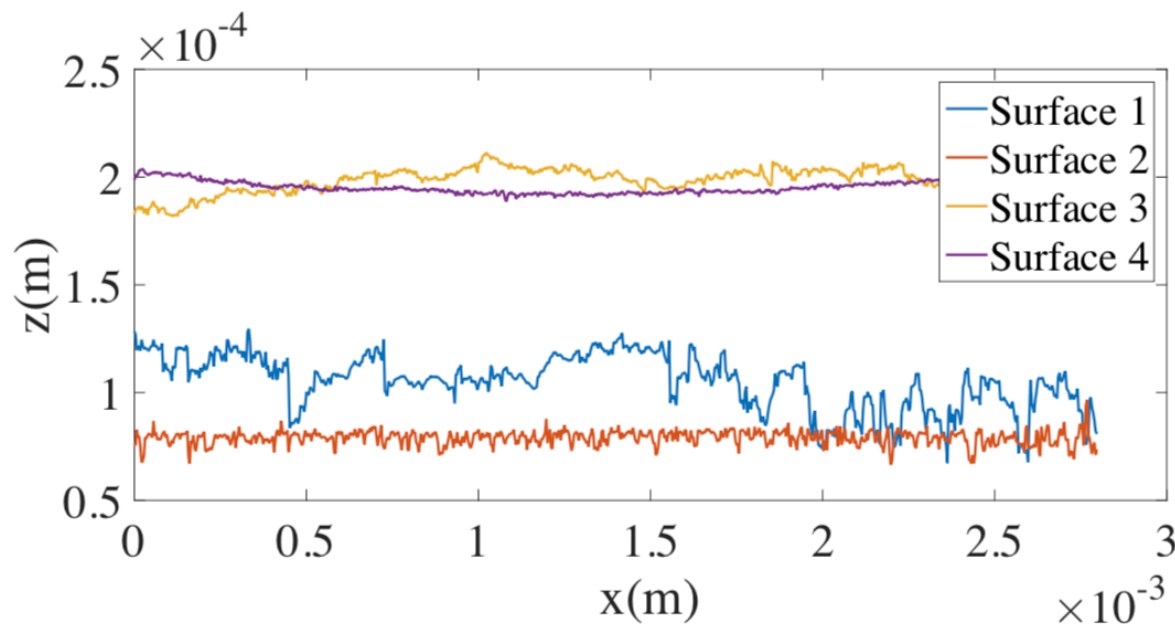
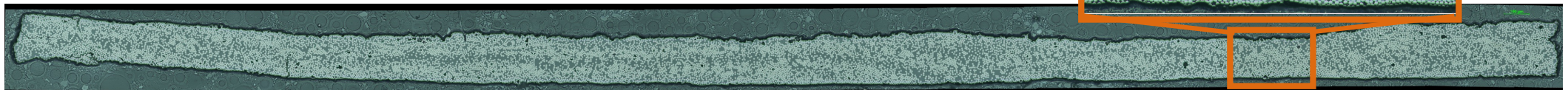
Material characterization : interface/impregnation/fibres repartition

# Case study

Mat2



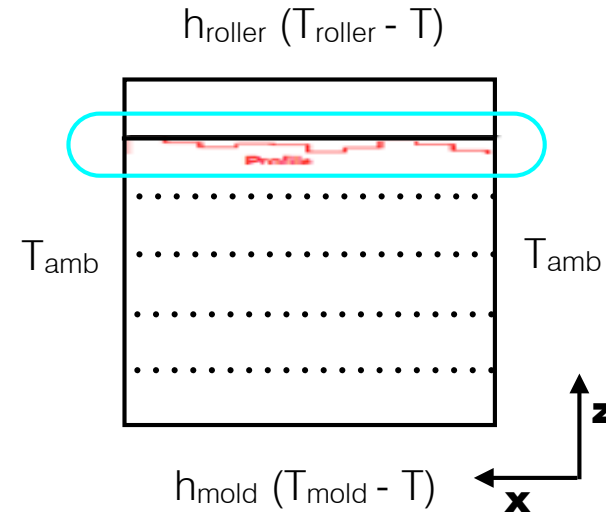
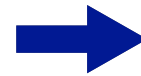
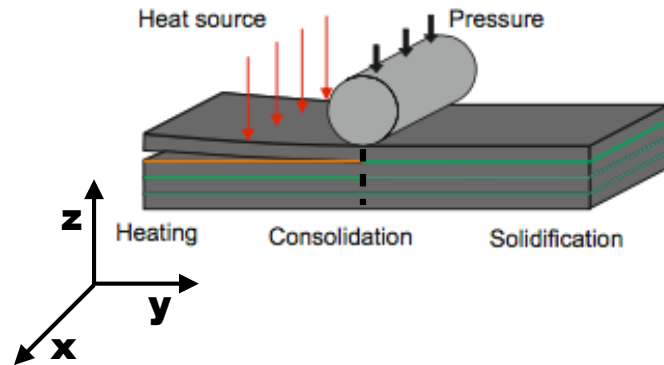
Mat3



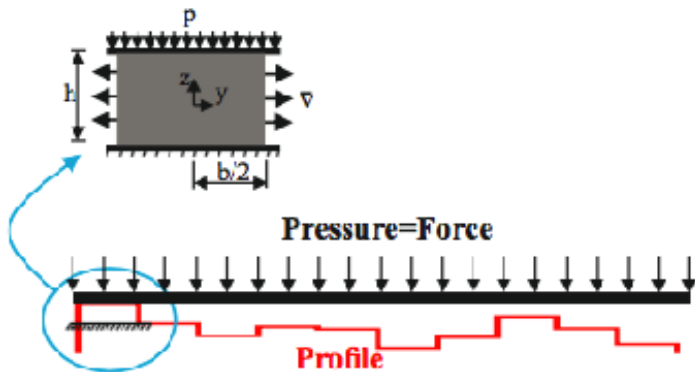
Surface	$R_a$ ( $10^{-6}m$ )	$R_t$ ( $10^{-6}m$ )	$R_s$ ( $10^{-6}m$ )
S1	2.7	34.0	43
S2	2.1	25.3	13
S3	0.8	10.5	103
S4	0.4	4.5	57

Micro-roughness (according to ISO 4287)

# Compression during consolidation



Scheme of compression of the profile: each asperity as a squeeze flow assuming lubrication hypothesis



$$-\dot{h} = \frac{2nh^{2+\frac{1}{n}}}{\mu + 2n\mu} \Delta P$$

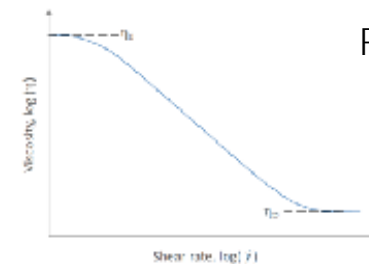
$$\mathbf{v} = \alpha^{-1+\frac{1}{n}} \frac{nh^{1+\frac{1}{n}}}{\mu + 2n\mu} \nabla P$$

Viscosity depends on temperature

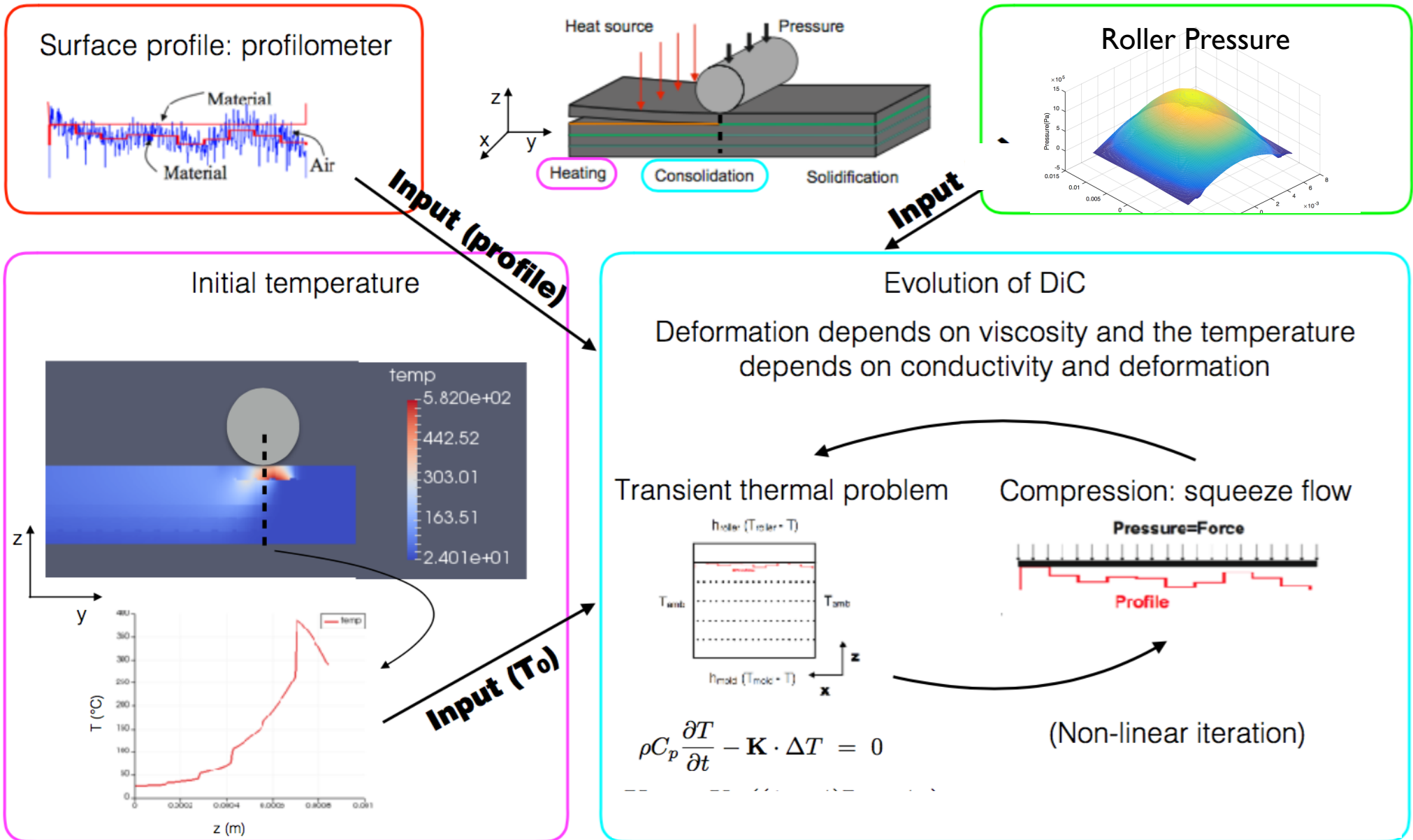
$$\tau = \mu \dot{\gamma}$$

Power-law constitutive equation

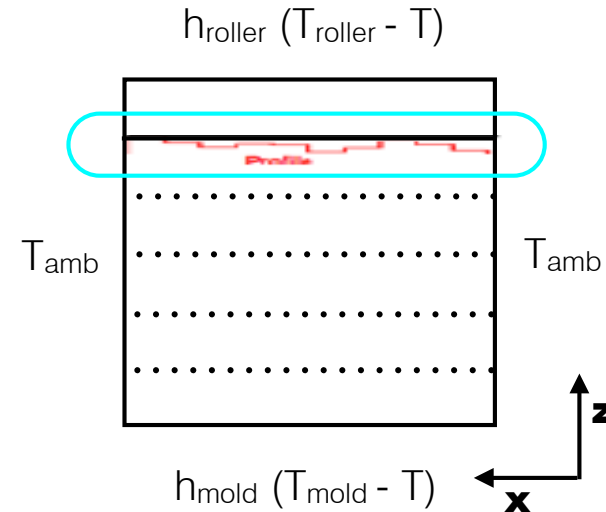
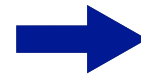
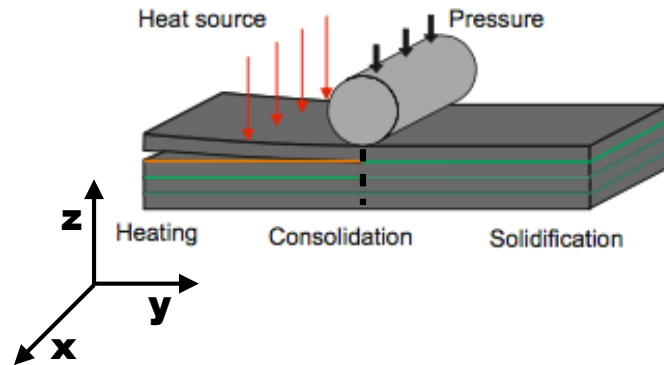
$$\mu = K (\dot{\gamma}_{eq})^{n-1}$$



# Dic Evolution Scheme



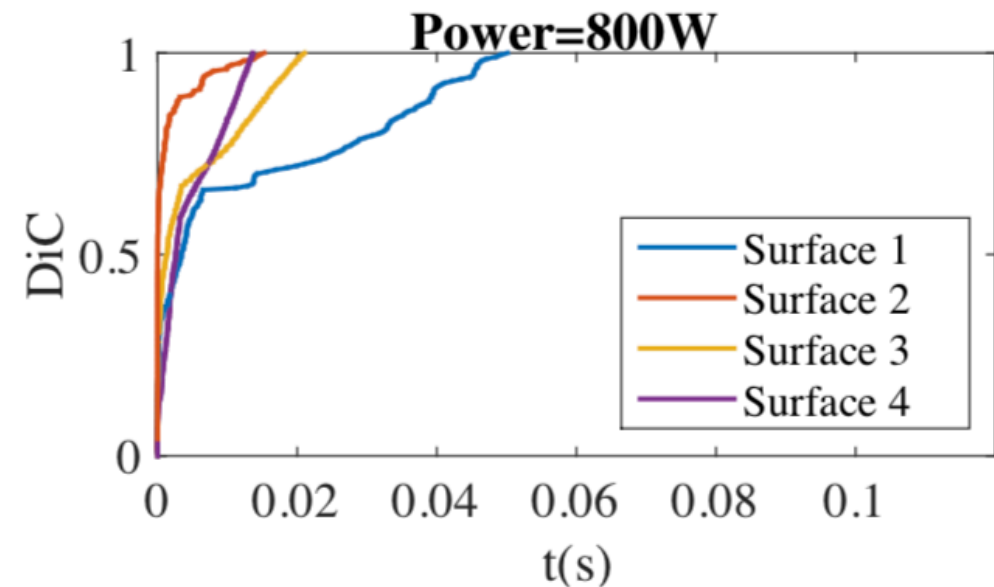
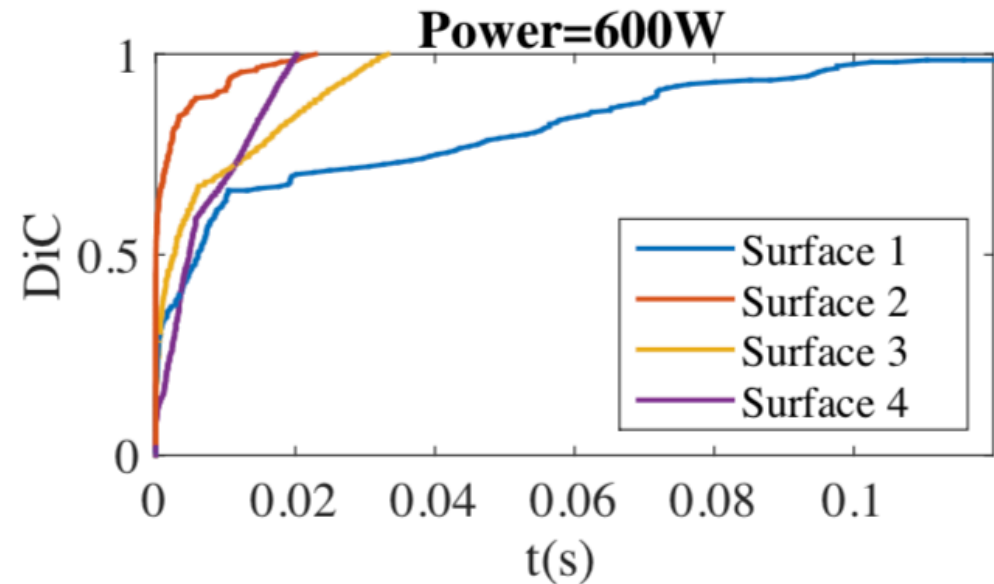
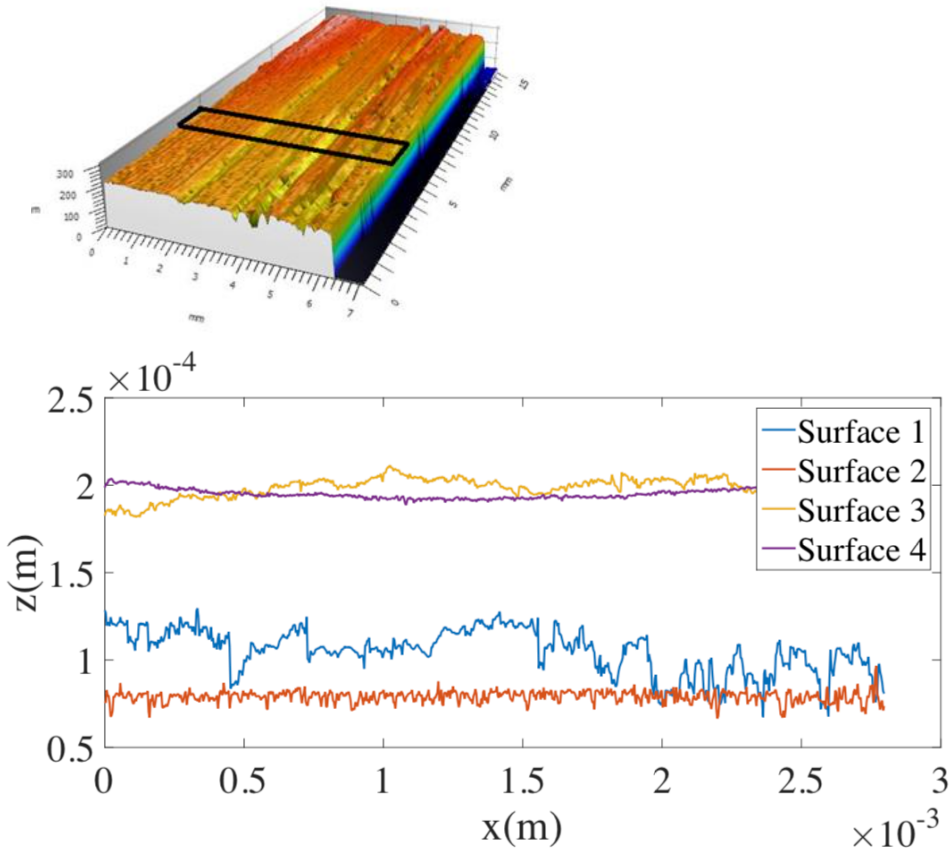
# Compression during consolidation



Simulation 'standard' parameters : Material, Process and Boundary conditions

Parameters of simulation			
$\rho C_p$	$2.2 \cdot 10^6$	$\mathcal{F}$	$600 \text{ N}$
$n$	$0.65$	$K_m$	$0.5 \text{ W}/(\text{m K})$
$K_a$	$0.024 \text{ W}/(\text{m K})$	$h_c$	$4000 \text{ K m}^2/\text{W}$
$h_{air}$	$10 \text{ K m}^2/\text{W}$	$h_{mould}$	$2500 \text{ K m}^2/\text{W}$
$h_{roller}$	$2000 \text{ K m}^2/\text{W}$	$V_{laser}$	$0.1 \text{ m/s}$
$m$	$6$	$T_{amb}$	$25 \text{ C}$
$T_{Mould}$	$25 \text{ C}$	$P_{laser}$	$720 \text{ W}$

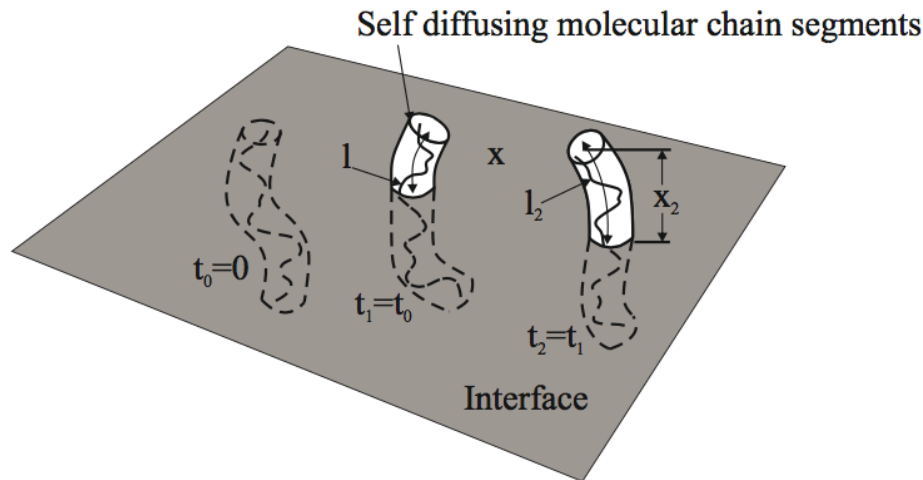
# Case study - Dic evolution vs Power





# Physics needed

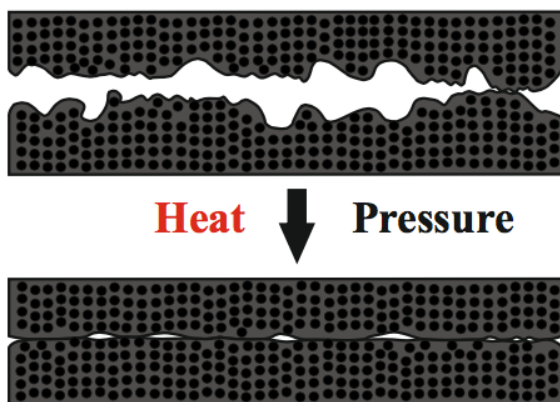
## Healing



- Molecules diffuse across the interface
- Reptation theory depends on temperature

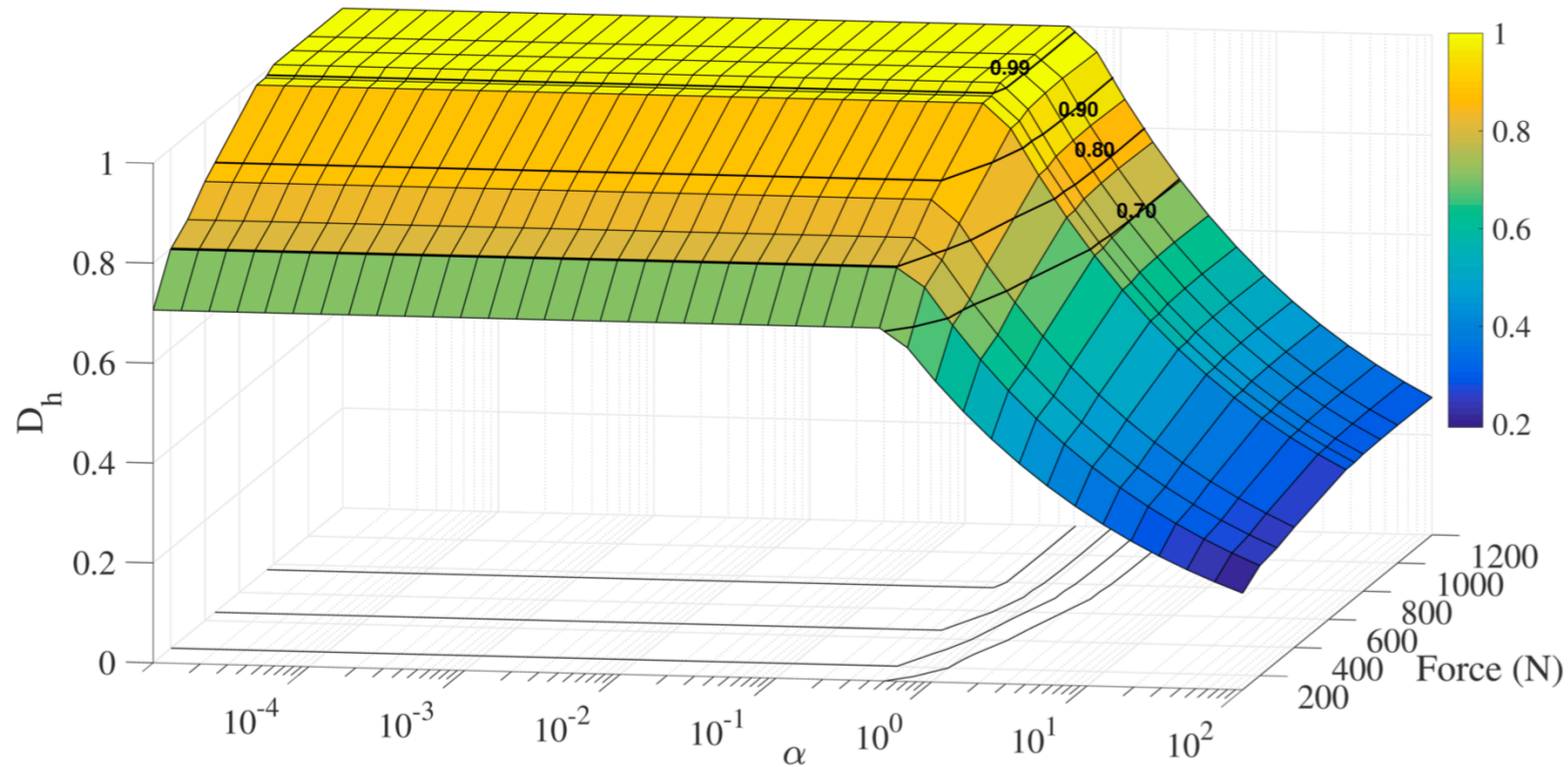
$$D_h = K(T) \cdot (t)^{1/4}$$

## Intimate Contact



- Evolution of area in contact
- Viscosity depends on temperature

# Case study - Dh evolution vs ...

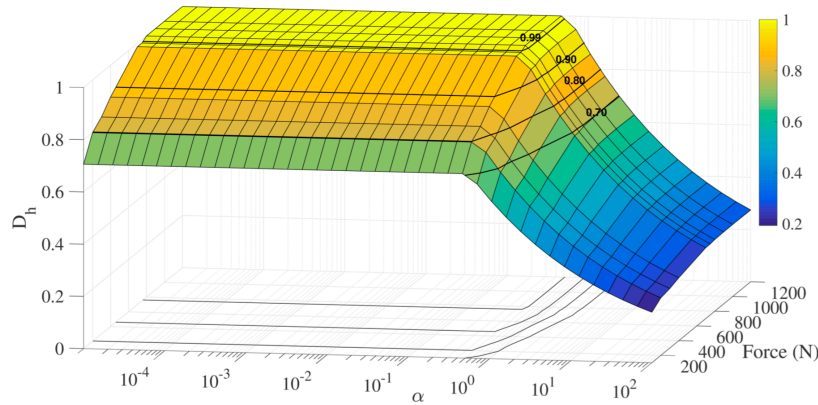


$$D_h(t) = \frac{\sigma}{\sigma_\infty} = \left( \int_0^t \frac{dt}{t_w(T)} \right)^{1/4}$$

Degree of healing

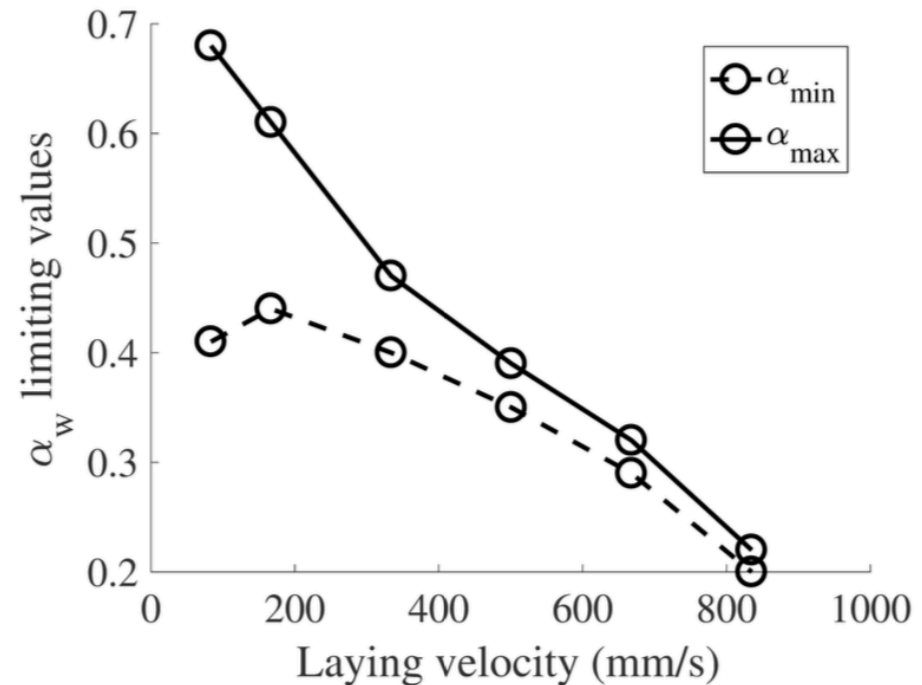
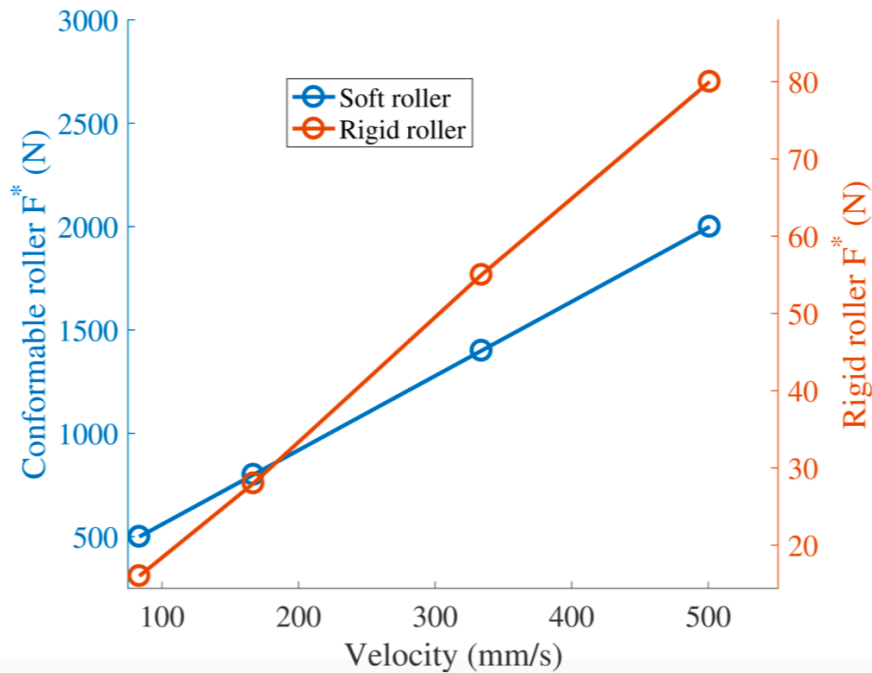
$$t_w = \alpha_w \cdot t_{rep}^{PEEK}(T)$$

# Case study - Dh evolution vs ...



$$D_h(t) = \frac{\sigma}{\sigma_\infty} = \left( \int_0^t \frac{dt}{t_w(T)} \right)^{1/4}$$

$$t_w = \alpha_w \cdot t_{rep}^{PEEK}(T)$$



# Conclusion & perspectives

This study aims at giving **some key elements** for **quickly designing the most efficient and robust ATP Process**.

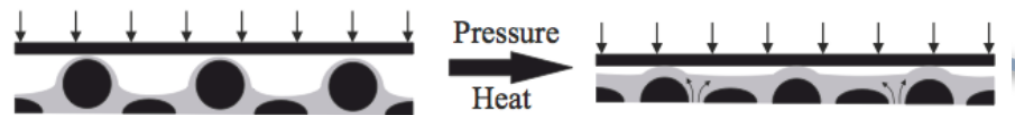
To do so, effort are gathered around the proposal of a modular simulation tool of the Process allowing a fine computation of the interply consolidation evolution.

A **very fine modeling** of the surface is **compulsory** to have a correct prediction of its evolution & further understanding of the **needed desired prepreg features**.

So, the interface is represented in a wavelet basis : allowing a **multi-scale representation**.

Today the compression of the **real geometry** is carried with lubrication hypothesis but the improvement of this point is actually in progress.

Actual work is also done improving the rheological modelisation of the interface during its compaction.



# Conclusion & perspectives

We have shown in this presentation, some results regarding the effect of the initial surface roughness of the prepreg or the importance of the reptation time on the consolidation evolution.

Many others parameters (either material and/or process) could be explored.

Experimental validation and understanding are still in progress to specify the dreamed materials dedicated for ATP thermoplastic process that will allow to reach the dreamed in situ consolidation

The packaging of a modular simulation tool being also an action in progress.

# Keys for designing the most efficient and robust in-situ TP ATP.

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